

What insects can tell us about the origins of consciousness

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How, why, and when consciousness evolved remain hotly debated topics. Addressing these issues requires considering the distribution of consciousness across the animal phylogenetic tree. Here we propose that at least one invertebrate clade, the insects, has a capacity for the most basic aspect of consciousness: subjective experience. In vertebrates the capacity for subjective experience is supported by integrated structures in the midbrain that create a neural simulation of the state of the mobile animal in space. This integrated and egocentric representation of the world from the animal's perspective is sufficient for subjective experience. Structures in the insect brain perform analogous functions. Therefore, we argue the insect brain also supports a capacity for subjective experience. In both vertebrates and insects this form of behavioral control system evolved as an efficient solution to basic problems of sensory reafference and true navigation. The brain structures that support subjective experience in vertebrates and insects are very different from each other, but in both cases they are basal to each clade. Hence we propose the origins of subjective experience can be traced to the Cambrian.

subjective experience | primary consciousness | vertebrate midbrain | central complex

Consciousness is marked by the presence of subjective experience: In the philosopher's term of art, there is "something it is like" for us to be aware of the world (1). Neurotypical adult humans are obviously conscious. So are young human children, although we recognize that the nature of consciousness in children is different from that of adults and changes rapidly as children develop. Plausibly, some animals also have the capacity for some forms of consciousness—at least, it certainly seems odd to insist that the inner life of a chimp goes on entirely in the dark. However, consciousness also gives out somewhere. Plants do not have it. It would be surprising if jellyfish did. Where to draw the line between what is conscious and what is not, and how to justify drawing that line, remain hotly debated questions.

These debates are especially difficult when it comes to assessing potential consciousness in invertebrates. Methodological challenges are partly to blame. The three most common methods of studying consciousness in humans—verbal report, behavioral demonstrations, and neural correlation with conscious activity—generalize poorly to invertebrate models. Nonhuman animals cannot give verbal reports about

what they are experiencing. There have been attempts to deploy to animals behavioral paradigms that are considered evidence of conscious processing when successfully performed by humans (2–4). This introduces a strong bias toward anthropomorphic performance by animals. As skeptics are quick to note, we have no guarantee that animals that behave like humans do so because they have the same subjective experiences that humans do. (Indeed, establishing this is precisely the issue.) Further, the bias toward clever animals is itself distorting. Many invertebrates live comparatively simple lives, without complex forms of communication and social behavior. If one cares about the basic capacity for consciousness and where it came from, one should be prepared to accept that the origins of consciousness may lie in animals that do only very boring, unclever things.

The search for the neural correlates of consciousness (NCCs) (5) is often framed as avoiding the pitfalls of purely behavioral research. NCC research focuses on the contents of particular conscious experiences, rather than the overall capacity for subjective experience (6). NCCs may thus be a poor guide to the more basic shared capacity to have any conscious

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experiences at all. In practice, NCC work also tends toward the anthropocentric, and the best paradigms are still difficult to extend to invertebrates. NCC results thus tend to be biased toward complex cortical structures and cannot generalize to animals lacking a cortex.

In this review, we will suggest an alternative approach to studying the capacity for subjective experience in invertebrates. Neuroethological approaches have made great advances in determining how neurobiological mechanisms within the insect brain generate adaptive behavior. We argue that knowledge of these mechanisms can ground an evidence-based inquiry into the capacity for consciousness in insects. We begin our argument by discussing the basic features of the simplest forms of consciousness, the capacity to have subjective experience (7). We then consider structures that support the capacity for subjective experience in humans. Following Bjorn Merker (8, 9), we argue that the human midbrain subserves the basic capacity for subjective experience. It does so in virtue of producing an integrated simulation of the state of the animal's own mobile body within the environment. We then argue that the insect brain performs similar functions, even though the anatomy of the insect brain is very different from that of vertebrates. Insects have specialized brain structures that solve the same basic problems by producing the same kind of unified model. We therefore conclude that if subjective experience is indeed supported by midbrain structures in humans, then insects also have the capacity for a form of subjective experience.

Finally, we propose that a capacity for subjective experience probably evolved early in the history of animal life for specific animal clades. We thus suggest that the study of insects gives a unique comparative perspective on the mechanisms and evolution of consciousness.

Subjective Experience and the Vertebrate Midbrain

Behavioral researchers have realized the need to distinguish different levels of consciousness. There are many classifications (7), but each posits a basic form of consciousness that consists of a direct awareness of the world without further reflection upon that awareness. This basic level has been termed primary consciousness (10), core consciousness (11, 12), phenomenal consciousness (13), or "I" consciousness (14). The defining feature of this most basic level of consciousness is the appearance of the capacity for subjective experience.

Humans are capable of more complex forms of consciousness. We can reflect upon our own mental states, for example, which is why verbal reports are so valuable. The levels corresponding to these higher capacities are variously termed self-reflexive consciousness (7), access consciousness (13), higher-order awareness (10), or "me" consciousness (14). These higher forms of consciousness require more than the mere capacity for subjective experience: the ability to represent one's own subjective experience to oneself, awareness of oneself as a self, the possession of the concept of experience, or full linguistic capability.

We mention these more complex levels of consciousness to bracket them off. It is contentious whether any other higher vertebrates possess them; we think it exceedingly unlikely that any invertebrates do. Our argument thus concerns only whether insects have subjective experience. Because subjective experience is a simpler phenomenon than self-reflexive consciousness, one might reasonably expect it to be more widespread in the animal kingdom, and evolutionarily older.

There is now considerable evidence that, in humans, subjective experience can exist in the absence of self-reflexive

consciousness, and that the two are supported by different neural structures. Midbrain structures, rather than cortex, seem to be especially important. Merker (8, 9), Parvisi and Damasio (11), Damasio and Carvalho (15), and Mashour and Alkire (16) have all argued that the integrated structures of the vertebrate midbrain are sufficient to support the capacity for subjective experience.

Merker (8) notes that subjective experience is remarkably sensitive to damage to midbrain structures. Conversely, there is evidence of preserved consciousness even in patients who lack a cortex (9). Further, although cortical damage can have profound effects on the contents of consciousness, damage to any portion of the cortex alone can spare the basic capacity for subjective experience (17–22). Cortical damage alone can have profound effects on the contents of consciousness, but even massive cortical damage seems to spare subjective experience itself (8, 17, 18). Indeed, there is evidence of residual conscious awareness in patients with severe cortical damage who are otherwise unresponsive to the world, suggesting that preserved subcortical structures may continue to support subjective experience (23, 24). Although the mechanism of anesthetic action is still debated (25), there is increasing evidence that the effect of anesthetics depends on the disconnection of cortical circuits from subcortical structures rather than on their direct cortical activity (26, 27). Anesthetics (28) or electrical stimulation (19), which affect cortical midline structures without affecting subcortical structures, do not abolish consciousness; they instead produce unresponsive but conscious dreamlike states. Conversely, emergence from anesthesia (16, 29) and coma/vegetative state (30) are predicted by the reengagement of subcortical structures and reintegration of those structures with cortical circuits. Other authors have noted the powerful subcortical effect of drugs, endogenous peptides, and direct stimulation on primitive motivational states (12, 16, 31).

In sum, there is good evidence that subcortical structures underlie the basic capacity for subjective experience in humans. This is not to say that the cortex is unimportant for conscious experience, of course. Rather, the proposal is that subcortical structures support the basic capacity for experience, the detailed contents of which might be elaborated by or otherwise depend upon cortical structures (32).

How the Vertebrate Midbrain Supports the Capacity for Subjective Experience

We will adopt and expand the account given by Merker (8), who argues that subjective experience arises from interacting midbrain and basal ganglia structures creating an integrated simulation of the state of the animal's own mobile body within the environment.

Merker suggests that an important function of the midbrain is to combine interoceptive (stimuli arising from within the body) and exteroceptive (stimuli external to the body) sensory information. Information on the environment, and the location and movement of the animal within it, is processed within the roof of the midbrain (the tectum, or colliculus in mammals). Information about homeostatic needs is processed within the floor of the midbrain (the hypothalamus and associated structures). Nuclei located between these poles integrate this information to produce a unified multimodal neural model of the spatial location of resources relative to the animal, which is coupled to, and weighted by, the extent to which different resources are needed by the animal (8) (Fig. 1A). Vertebrates organize their behavior by reference to this integrated model of the environment rather than by reacting to independent sensory inputs (8, 33).

In mammals the superficial layers of the superior colliculus (SC) receive topographically organized visual inputs (34), whereas the deeper layers receive topographically organized visual, auditory, and somatosensory input (8, 15, 33, 35). In some species, specialized spatial senses such as infrared and magneto- and electrosenses and echolocation send topographically organized inputs to the SC (8, 36–38). Within a species, the sensory topographic maps in different layers of the SC are superposed, meaning specific regions of space are represented by similar points in each overlaid sensory map (39). This arrangement allows a point of convergence for processed spatially structured information, in turn allowing an integrated sense of space that includes the position, state, and movement of the body (9, 40–42).

Organizing behavior by reference to an integrated simulation of the state of the mobile body in space also provides an efficient neural solution for resolving the confusing sensory input caused by self-motion [the so-called reafference problem (43)]. Bodily motion causes widespread changes in sensory input, yet we seamlessly disambiguate our own movements from the movements of objects around us. In mammals, the multisensory inputs to the SC include inputs from the vestibular system (44), information on eye position (45–47), and somatosensation (8). This allows the influence of self-motion on the sensory fields to be factored out of the constructed sensory model of the environment (42). Resolving the reafference problem is a key function for the mammalian SC, which is why this region is vital for organizing motion in space for directed attention, reaching, and grasping for targets (41, 48–50).

For active animals with well-developed spatial senses, it is computationally more effective to resolve the reafference problem once for a unified sensory model than to resolve it in a dispersed and peripheral way for each sense independently. Further, different senses are affected by reafference in different ways and contribute different information on how the body is moving. Reafference can thus be resolved with greater accuracy and precision by integrating information from multiple senses (9).

For mammals, the processing performed within the SC constructs something akin to a simulation of the moving body in the environment (9). For humans at least, this spatial “model” is further enhanced by processing within the subcortical dorsal pulvinar (one of the thalamic nuclei, part of the basal ganglia) (32), which adds color, three-dimensionality, and an egocentric first-person perspective to the human conscious experience of space. A major benefit of this integrated spatial simulation is that it allows animals to interact with objects in a qualitatively different set of ways than simple stimulus-bound organisms could manage. Animals that navigate by reference to a simulated spatial model can actively seek out and navigate toward hidden objects. It is worth emphasizing what is implied by such an apparently simple navigational ability. A food source concealed behind a barrier, for example, is neither part of an organism’s current sensory input nor accessible by following a simple vector with its origin at the animal’s current position. Navigation requires a unified metric space that allows for effective computation of relative position after both actual and hypothetical translations within that space (51–54). This is beyond the primary sensory input but can be supported by a simulation of the environment constructed from that input (55).

The midbrain also provides the capacity to resolve competing behavioral priorities or motivations and rank needed resources by both urgency and availability. The floor of the midbrain is formed by the hypothalamic structures and associated nuclei whose function is to integrate information from the nervous and endocrine systems, to harvest and respond to information on the physiological status of the organism, and to motivate behavior to maintain a homeostatic optimum (56) (Fig. 1B). Maintaining homeostasis requires actively seeking needed resources; hence, midbrain structures are critical for the initiation and direction of a wide range of goal-directed behavior (15, 56). Integrative structures within the midbrain and basal ganglia, including the periaqueductal gray, substantia nigra, ventral thalamus, striatum, and midbrain reticular formation, combine this information on introspective assessment of state with exteroceptive assessment of

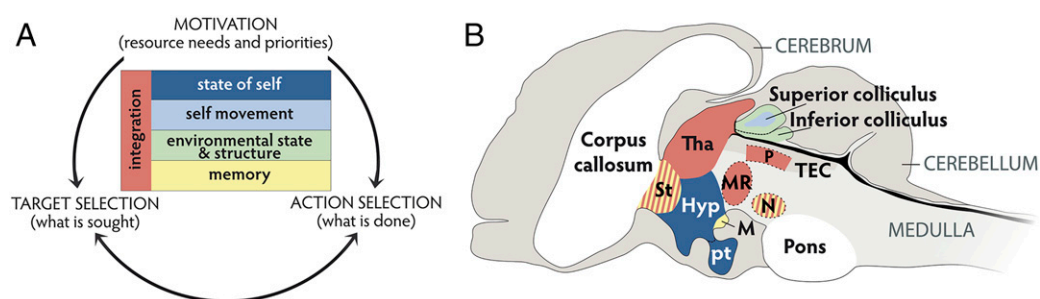


Fig. 1. Structures of the vertebrate midbrain (not to scale) supporting the behavioral “core control system.” The vertebrate midbrain supports an integrated multisensory model of the state of the animal in space, which supports effective decision making. (A) Decision making involves an assessment of what is needed and where and how the needed resources can be obtained. Decision making can therefore be considered to involve three domains: internal motivations, target selection, and action selection [adapted from the “selection triangle” proposed by Merker (8)]. These domains interact and can be resolved by referencing an integrated neural model that contains information on the state of self, self movement, environmental state and structure, and memory of prior experience. These elements of the neural model are supported by midbrain structures (B). As a simplification, regions are colored according to their primary function(s) in the neural model described in A. The superior colliculus [part of the tectum (TEC) forming the roof of the midbrain] receives topographically organized multisensory input and creates an integrated neural model of the organism moving in space (8). The floor of the midbrain is formed by the hypothalamic structures (Hyp) and associated nuclei [pituitary (pt) and mammillary bodies (M)] that collate information on the physiological status of the organism referenced with prior experience, to identify needs to maintain a homeostatic optimum (15, 56). Integrative structures within the midbrain and basal ganglia, including the periaqueductal gray (P), substantia nigra (N), thalamus (Tha), striatum (St), and midbrain reticular formation (MR), integrate these sources of information (8, 33) (A). In advanced vertebrates the cortex and hippocampal structures clearly have a very strong input in to this system, but this midbrain system is not dependent on cortical inputs to function (140) and is highly conserved across all vertebrate lineages (33).

location in space to collate and resolve competing motivations, prioritize resources, and select targets and actions (8, 33).

Midbrain and basal ganglia structures thus provide an effective and efficient neural solution for decision making (Fig. 1A). Competing and potentially conflicting behavioral responses that might be stimulated by different inputs can be resolved within a single behavioral control system (33, 57). Target selection and action selection must interact (Fig. 1A) because each domain informs the others. Motivational factors will influence the prioritization of targets and therefore action selection, but the location of targets will also influence which is selected, and which actions should be taken (8). Merker (8, 9) describes this as a “behavioral core control system” within which these decision domains can be resolved. Analyses and modeling of basal ganglia function in vertebrates have emphasized how drawing together all evidence for different possible actions within a unified neural system enables an effective and efficient solution for action selection, without having to posit a higher-level decision maker reflecting on the decision (57–59).

Placing the basic capacity for subjective experience in subcortical structures does not rule out a role for the cortex and other subcortical systems (including hippocampal systems) in conscious experience. The contents of subjective experience will vary enormously between species, and that variation will depend in part on the degree of elaboration of cortical structures. However, the capacity for subjective experience is not dependent on containing any particular contents (9, 32). The basic capacity for subjective experience that the midbrain supports is rather a capacity to have any subjective contents at all.

The midbrain thus provides a forum for specific contents to be integrated together with more basic survival-oriented machinery. However, the modeling function of the midbrain does not require some overseer that reflects on the model [the fallacy of the “Cartesian theater” (60)]. Decisions arise directly from this model, not from some further decision-making process informed by the model.

It is worth distinguishing the current proposal for the substrate of subjective experience from other, related, accounts. Like global workspace theories (61), we emphasize the role of consciousness in bringing together disparate brain processes into a common arena. Global workspace theories have a strongly cortical bias, however, focusing on the contribution of human fronto-parietal regions to reflective self-awareness of our mental states. It is unclear how widely this generalizes. We propose that even for invertebrates—which lack anything remotely like an elaborate cortex—holistic integration is essential for the more basic, evolutionarily ancient behavioral demands of action selection, refference adjustment, and navigation. Further, insofar as cortical processes can matter to the organism, we argue that they must ultimately be integrated via midbrain mechanisms (58, 62). As Merker (8) puts it, the midbrain control system is “anatomically subcortical [but] functionally supra-cortical.”

Like information integration theories of consciousness (63–65), we claim that consciousness performs an important synthetic role. Unlike information integration theories, however, it matters which information is unified. Subjective experience requires the construction of an integrated neural simulation of the agent in space, weighted by the state of the agent. This simulation is constructed from appropriate integration of afferent, efferent, and homeostatic information. Just integrating information is not sufficient for subjective experience, no matter how complex or well-integrated the information. Information integration theorists have also tended

to take a more liberal and graded view of consciousness, suggesting that even simple circuits such as a photodiode attached to memory might have a “modicum of experience” (65). By contrast, our theory implies that there is a definite cutoff point below which there is definitely not subjective experience (a point to which we will return).

Unified modeling provides effective solutions to the refference problem and action selection for motile animals with developed spatially coherent senses (such as vision) (9, 66, 67). As such, it is not surprising that the vertebrate midbrain behavioral core control system evolved early on in the group and has been largely conserved since. Lampreys (primitive jawless fish) have functional homologs of all of the key nuclei involved in the vertebrate behavioral core control system (*sensu ref. 8*) including a well-developed tectum to process spatially structured visual information (68, 69) and equivalents of the basal ganglia system to resolve action and target selection (67, 70). It is thus a commitment of our model that subjective experience is likely to be universal among the vertebrates. What about invertebrate groups?

Consciousness in Insects

The insects are an extremely diverse group, but all insect brains have a common anatomical plan (Fig. 2). The nervous system contains an enlarged cephalic ganglion (a brain) specialized for sensory processing and integration. This is linked by paired ventral nerve cords to a series of smaller ganglia for the thoracic and abdominal body segments. The insect nervous system has frequently been stereotyped as decentralized (71), with the cephalic ganglion acting simply as a region of sensory input that triggers motor responses organized by the segmental ganglia (8, 71). This interpretation is incorrect and outdated. The insect brain resolves action and target selection, processes sensory information, and clearly executes a command function over the behavioral system (72).

A compelling demonstration of the command function of the insect brain for the total behavioral system of the insect is the effect of focused injection of neurotransmitter agonists and antagonists to the region of the central complex (CX) of the insect brain. The parasitoid jewel wasp *Ampulex compressa* uses its ovipositor to inject venom containing GABA and octopamine antagonists into the CX of its cockroach prey (72, 73). The venom is not paralytic: the cockroach is still able to perform many basic actions. Rather, the pharmacological lesion to the central protocerebrum containing the CX disrupts the cockroach’s behavioral program, rendering it entirely passive so that it will not struggle as the wasp leads the cockroach by the antennae into its burrow. The effect of *Ampulex* venom on the cockroach brain is thus to eliminate the capacity of the roach to organize and initiate behavior (73). This example shows that the central brain structures are key for the initiation and direction of movement in cockroaches and crickets (74, 75).

Further, the CX of the insect brain seems specialized for the processing of spatial information and organization of movement (76). As such (we argue), it performs functions analogous to the vertebrate tectum/colliculus (Fig. 2). Like the vertebrate tectum/colliculus, the CX plays a crucial role in processing multiple sources of spatial information drawn from different senses. Many insects are sensitive to plane-polarized light, a vital celestial navigational cue. In locusts (*Schistocerca gregaria*) information on the distribution of polarized light in the sky is processed by the CX, which creates a central polarotopic representation of the sky polarization pattern (77). Outputs from this system could provide

compass-like information to stabilize the direction of moving insects relative to the external celestial cue (78). This function for the CX has been described in locusts and butterflies (*Danaus plexippus*) but may be common across insect orders (79). Further, in *S. gregaria* (80), the cockroach *Blaberus discoidalis* (75), and *Drosophila melanogaster* (81, 82), the CX encodes topographically organized visual information on moving objects and is capable of factoring out the confounding effects of visual motion generated by self-movement from moving objects in the environment (82). In *Drosophila*, neural activity within the CX encodes the fly's heading relative to visual landmarks in the environment and presumably enables the fly to maintain a course relative to those landmarks (83). The CX is also vital for flies to learn spatial tasks (84, 85).

Collectively these studies emphasize the capacity of the insect CX to represent visual space such that the insect can orient and navigate. However, the CX processes more than just visual information. In cockroaches (86), *Drosophila* (83), and crickets (74), the CX also encodes topographically organized mechanosensory and proprioceptive information, corrected for reafference, to resolve the movements and orientation of the body and limbs in space. The CX is necessary for producing actions that involve coordination of limbs on both sides of the body (such as turning), and also for judging distance in targeting and reaching (87). The various topographically organized sensory maps are layered in *Drosophila* (79), and it would seem the sensory maps are integrated because the encoding of azimuth in the *Drosophila* CX can switch seamlessly between a reliance on visual landmarks in the light to a reliance on proprioceptive cues in the dark (83).

New electrophysiological studies of the visual interneurons of the lobula of the *Drosophila* brain have shown how a flying fly can resolve the reafference problem (88). Visual interneurons that register optic flow in the visual field receive a motor-related input when the fly turns, which precisely counters the visual stimulation of the neurons caused by the turn (88). The electrophysiological data support von Holst and Mittelstaedt's (43) classic theory, and inferences from insect behavioral studies (89–91), that an "efference copy" of a motor action is sent to the visual system to silence the specific image motion caused by a voluntary turn. The motor-related input to the lobula is specific and anticipatory of the motor action, cautiously supporting a forward model of action selection (where modeling of the movement and its consequences precedes the movement itself) (88, 92). Although we still do not know how the efference copy to the lobula is generated, it seems increasingly likely that CX circuits are involved.

One of the crucial functions of the CX is thus to generate a neural simulation of the state of the moving insect in space. This simulation forms part of the insect behavioral core control system (Fig. 2). The CX outputs to, and receives input from, the protocerebrum (P) of the insect brain, especially the lateral accessory lobe which is a point of convergence for sensory information. These include both direct inputs from the sensory lobes and indirect inputs via the CX and mushroom body (MB) pathways (Fig. 2), which are a locus for memory of past experience. The P is premotor, and emerging evidence suggests that competitive processing within structures of the P contributes to effective action selection based on all available sensory information (93–96).

In sum, new functional analyses of the insect brain emphasize how it supports a behavioral core control system that is functionally analogous to that of the vertebrate midbrain (Fig. 2). This no doubt supports much of the dynamic and flexible behavior for which some insects are famous. Some of the central-place foraging ants and bees have remarkable navigational skills and

spatial memory and are clearly able to organize their behavior with respect to more than simply their immediate sensory environment. They will perform targeted searches in appropriate locations and at appropriate times (97) for resources they have experienced previously. Several insect species have been shown to be able to plot novel routes based on learned landmarks and goals, evidencing a spatial relation of landmark information (98, 99). The honey bee dance communication system requires a dance follower to determine a flight vector relative to celestial cues from symbolic and stereotyped dance movements (100).

All these behaviors require a form of neural modeling of space. There is now both behavioral and electrophysiological evidence that the neural modeling of the environment performed by insects involves multiple layers of filtering of sensory information to support selective attention to stimuli that are salient and suppression of representation of irrelevant stimuli (101–104). The amount and amplitude of firing activity within certain defined frequency bands in the central brain of tethered flies in response to visual stimuli is dependent on whether the fly is visually fixed on the stimulus or whether the context of the stimulus has changed (101). This change in neural activity has been described as a neural signature of "salience" in insects (101, 102). The brain region in which this occurs includes the point of interaction between the MB, CX, and P circuits, and the electrophysiological response is dependent on a functioning MB (101, 102).

These findings show how the brain responds to environmental stimuli in insects are not driven simply by the primary sensory input, but rather by egocentric characteristics: whether the context of the stimulus needs to be updated or whether the stimulus is a point of immediate navigational reference (101, 102). In essence, responses depend upon what the insect is attending to at that moment (104). In bees, even activity in the optic lobes is influenced by centrifugal input from the central brain to enhance

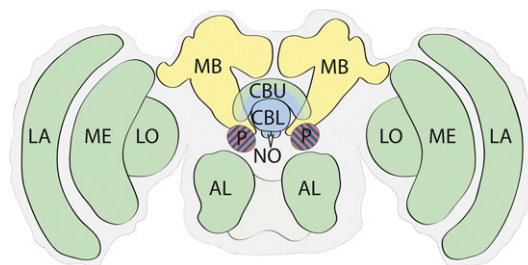


Fig. 2. Basic functional anatomy of the insect brain (not to scale). The structures of the insect brain create an integrated neural model of the state of the insect in space that is functionally analogous to that described for the vertebrate brain in Fig. 1. Regions are colored to reflect the major functions described in Fig. 1A. Vision and smell are primarily processed by dedicated sensory lobes, which function to refine and enhance sensory representations and enhance distinctions between similar stimuli (95, 141). Primary odor processing is performed in the antennal lobes (AL). Visual processing is performed by the lamina (LA), medulla (ME), and lobula (LO). The MB supports learning and memory (142–146). The CX is anatomically variable between insect orders but typically is composed of the central body upper (CBU), central body lower (CBL), and noduli (NO). It has several specializations for processing spatial information corrected for self movement (75, 76, 83, 87). The protocerebrum (P) is an anatomically complicated region. Modulatory and inhibitory connections to and within the protocerebrum convey information on physiological state (94, 95), and structures within the protocerebrum, particularly the lateral accessory lobe, are involved in integration of information, hence the hatched shading.

well-developed cephalic ganglia with structural similarities to extant crustacean and insect brains (134). We argue it is likely that a version of the extant insect behavioral core control system must have been present in at least some Cambrian arthropods to support their active foraging and hunting lifestyles. The CX is basal to the insect clade. Although there is some variation in the structure of the CX between insect orders, this structure features in all insects and crustaceans and is likely homologous to the arcuate body of arachnids (87, 135, 136), suggesting a form of the CX evolved before the radiation of insects, crustaceans, and spiders. Trestman (130) has argued that the spatial awareness and agentive behavior enabled by arthropod neural and sensory systems may have contributed to the arthropod radiation in the Cambrian as a consequence of the emergence of new forms of behavior such as hunting. It is plausible that some of the Cambrian fauna within both the basal vertebrate and arthropod groups had a capacity for subjective experience.

It is presently unclear whether the insect and vertebrate behavioral core control systems evolved independently. Strausfeld and Hirth (137) marshal commanding developmental, anatomical, and genetic evidence to argue a possible deep homology of the insect CX and associated structures with vertebrate basal ganglia structures. If this interpretation is correct, it would imply that a brain with a form of higher sensory integration center may even predate the divergence of these groups.

Moving Forward on Invertebrate Consciousness

We have argued that insects possess a capacity for subjective experience. Many find this a counterintuitive result. A natural place to take issue with our argument is with our reliance on Merker's proposal that the midbrain is sufficient to support subjective experience. Fair enough. Merker's theory is far from

universally accepted, and even otherwise similar theories may not (for all we have said) generalize to invertebrates. With Merker, we have emphasized the importance of a unified perspective on the world as a key feature of subjective experience (14). However, perhaps other neural features are also necessary for subjective experience, such as a representation of a temporal dimension (138). Perhaps insects lack these (though see ref. 139).

However, this kind of disagreement can be fruitful. If insects do not have subjective experience, why not?

What is important, from our perspective, is that either proposing or denying that insects have subjective experience should require telling an evidence-based structural, functional, and comparative story about the insect brain. We have downplayed behavioral data. Critically, we have not relied on evidence of unusual or clever achievements by insects. Rather, we suggest, behavior is important only insofar as it is a guide to understanding the underlying mechanisms by which behavior is generated.

We propose that arguing about what subjective experience is, and what is capable of it, is most productive when appealing to empirical neuroscience. We believe that it is on these structural, functional, and comparative grounds that questions about subjective experience—of insects or of any other animal—ought to be settled.

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